

## Wavelet analysis and scaling properties of time series

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We propose a wavelet based method for the characterization of the scaling behavior of nonstationary time series. It makes use of the built-in ability of the wavelets for capturing the trends in a data set, in variable window sizes. Discrete wavelets from the Daubechies family are used to illustrate the efficacy of this procedure. After studying binomial multifractal time series with the present and earlier approaches of detrending for comparison, we analyze the time series of averaged spin density in the 2D Ising model at the critical temperature, along with several experimental data sets possessing multifractal behavior.

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A large number of studies have been carried out to analyze scaling properties of fluctuations in time series. The studies have involved time series of dynamical variables from physical, biological, and financial systems [1,2]. For scaling analysis different approaches have been suggested and implemented, starting from the structure function method to wavelet transform modulus maxima (WTMM) [3–5] and the recent, detrended fluctuation analysis (DFA) [6–8] and its variants [9–11]. The difficulty in characterizing the scaling property stems from the fact that, the observed time series is very often nonstationary. Hence, it is essential to define fluctuations in a manner which takes proper account of nonstationarity.

In this Brief Report, we propose a method, based on discrete wavelet transform [12], to separate the trend in the time series from the fluctuations. The method is direct and suggests itself naturally from the basic concepts underlying wavelet decomposition, apart from being supplementary to the detrended fluctuation analysis. The fact that the so-called low-pass coefficients represent a coarse grained version of the data in wavelet transform and the built-in ability of the wavelets to have variable window sizes for coarse graining, makes it a natural tool for identifying fluctuations around trends at various scales. We use this method to examine scaling behavior of a time series. For the purpose of checking the efficacy of our procedure and comparison with multifractal detrended fluctuation analysis (MFDFA), we consider time series generated ( $10^6$  data points) from the binomial multifractal model [2], for which the scaling exponent is analytically calculable. The method has also been checked on Gaussian random noise. We then analyzed the time series of average spin densities ( $9 \times 10^5$  data points) in a simulation of the 2D Ising model on a  $256 \times 256$  lattice at the critical temperature  $T_c$ , where each update of the system in the simulation is taken as one time step [16,17]. These computer generated time series are shown in Fig. 1. Experimentally measured data [18] of ion saturation currents and floating potential in Tokamak plasma are shown in Fig. 2. These are then analyzed for their multifractal analysis.

Before we describe our approach in detail, it is worthwhile to give a brief summary of some basic features of scaling. For this purpose let  $x(t_i)$  denote the value of an observable at  $t_i = i\Delta t$ . The set  $x(t_i); i = 1, 2, \dots, N$  is then the time

series under consideration. A simple way to define fluctuations, for a stationary time series at time scale  $\tau_k = k\Delta t$ , is

$$\Delta x_i(\tau_k) = x(t_i + \tau_k) - x(t_i), \quad i = 1, 2, \dots, N - k. \quad (1)$$

These fluctuations are said to have scaling property, if the probability distribution function (pdf) of  $\Delta x_i(\tau_k)$  has the same form for different values of  $\tau_k$ . Further, the parameters that characterize the pdf depend in a well-defined manner on  $\tau_k$ . For example, for independent fluctuations with a Gaussian pdf, we have the well-known scaling results for the mean  $\epsilon(k\Delta t) = k\epsilon(\Delta t)$  and variance  $\sigma^2(k\Delta t) = k\sigma^2(\Delta t)$ . In general for all finite moments  $m_q$  of order  $q$ , this is expressed as

$$m_q = \langle |[\Delta x(k\Delta t)]|^q \rangle = \frac{1}{N-k} \sum_{i=1}^{N-k} |\Delta x_i(k\Delta t)|^q \sim (k\Delta t)^{\zeta(q)}, \quad (2)$$

where  $\zeta(q)$  is constant for monofractals. The Hurst exponent  $H = \zeta(q=2)$ , equals 0.5 for the Gaussian white noise. The scaling property of the pdf considered above implies that, the variability at different time scales in time series is fractal in nature; it is self-similar (more precisely self-affine). Monofractals with  $H < 0.5$  are long range anticorrelated and for  $H > 0.5$  the signal shows long range correlation. For time series of complex systems, it often turns out that scaling is present but the dependence of scale factor on  $q$  is not linear but decreases with increasing  $q$ . This type of scaling behavior is termed as multifractal.

The scaling (multiscaling) property of the time series arises from the corresponding property of the fluctuations. More precisely, in this connection, the probability distribution and the time correlations of the fluctuations are the properties of importance. There are complications and difficulties, if conclusions about the scaling behavior of a dynamical system, are entirely based on a finite length time series in presence of correlations. This is the case for most physiological and financial time series and the associated problems have been highlighted in Refs. [13–15].

The difficulties of standard multifractal formalism, based on the structure function method, led to the development of WTMM, a continuous wavelet transform based approach.

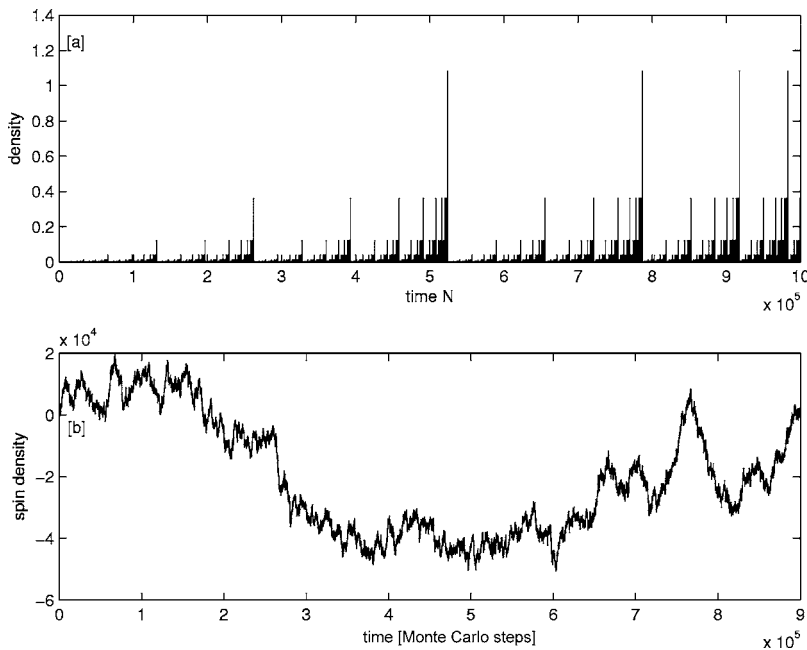


FIG. 1. Time series simulated through (a) binomial multifractal model and (b) 2D Ising model at critical temperature.

Although like the structure function method, this is also a global approach, the built-in advantage of wavelets in identifying scaling properties of data, made WTMM quite ideal in finding the multifractal behavior. In a later stage, the multifractal detrended fluctuation analysis (MFDFA) has been developed to tackle the nonstationary time series. The basic idea in the above approach is to isolate fluctuations in the data set, through multiple local windows, of varying sizes. For this purpose, once the window size is fixed, an appropriate fit, e.g., a polynomial fit, is employed to identify the trend and the fluctuations are then isolated, by subtracting the trend from the data points. The method we propose is based on the fact that, the low-pass coefficients in wavelet transform, resemble the data, albeit in an averaged manner. The extent of averaging depends on the level of wavelet decom-

position. It supplements the MFDFA, in the sense that, instead of a polynomial fit, one can use the appropriate low-pass coefficients for capturing the trend.

The basis elements in discrete wavelet transform, provide a complete and orthonormal set, unlike the continuous wavelets, wherein the basis functions usually comprise an overcomplete set. The two key members are the scaling (or father wavelet)  $\phi(t)$  and the mother wavelet  $\psi(t)$ , respectively, satisfying  $\int dt \phi(t) = A$  and  $\int dt \psi(t) = 0$ . Here  $A$  is a constant;  $\phi(t)$  and  $\psi(t)$  satisfy square integrability conditions apart from being orthogonal to each other. The two key operations, underlying the construction of a complete orthonormal basis set, are translation and scaling of the father and mother wavelets, which have strictly finite sizes. Translation by discrete steps brings in the index  $k$  to both father and mother

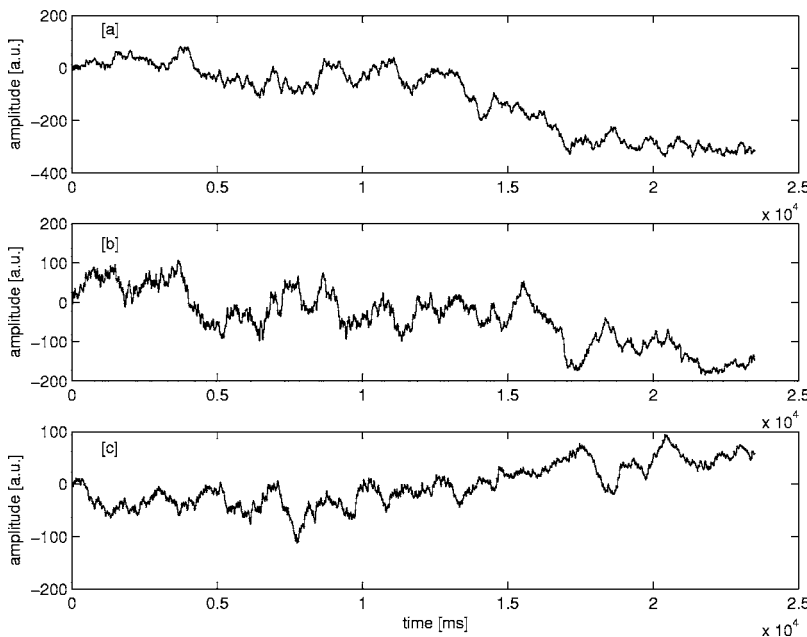


FIG. 2. Time series of, (a) ion saturation current (IC), (b) floating potential (FP), 6 mm inside the main plasma, and (c) ion saturation current (ISC), when the probe is in the limiter shadow. Each time series has approximately 24 000 data points.

wavelets,  $\phi_k(t) \equiv \phi(t-k)$  and  $\psi_k(t)$ . Producing daughter wavelets, copies of the mother wavelet, albeit thinner and taller, through scaling allows one to form a complete set. With the scaling index  $j$ , conveniently running from 0 to  $\infty$ , wavelets can be compactly written as  $\psi_{j,k}(t)$ , where  $\psi_{0,0}(t)$  is the original mother wavelet. The key equation underlying all wavelets is the multiresolution-analysis (MRA) equation,

$$\begin{aligned}\phi(t) &= \sum_n h(n)\sqrt{2}\phi(2t-n), \\ \psi(t) &= \sum_n \tilde{h}(n)\sqrt{2}\phi(2t-n).\end{aligned}\quad (3)$$

Here,  $h(n)$  and  $\tilde{h}(n)$  are the low- and high-pass filter coefficients satisfying the constraints,  $\sum_n h(n) = \sqrt{2}$ ,  $\sum_n h(n)h(n-2k) = \delta_{k,0}$ ,  $\sum_n \tilde{h}(n) = 0$ ,  $\sum_n \tilde{h}(n)\tilde{h}(n-2k) = \delta_{k,0}$ , and  $\sum_n \tilde{h}(n)h(n-2k) = 0$  originating from the normalization and orthogonality conditions mentioned above. Here  $n$  is the length of the filter coefficients. The MRA equation can be used to obtain recurrence relations

$$\begin{aligned}c_j(k) &= \sum_n h(n-2k)c_{j+1}(n), \\ d_j(k) &= \sum_n \tilde{h}(n-2k)c_{j+1}(n).\end{aligned}\quad (4)$$

Here,  $c_j(k)$  and  $d_j(k)$  are, respectively, the low-pass and high-pass coefficients at level  $j$ ; MRA equation implies that, both of these coefficients can be obtained from the next level low-pass coefficients alone. We note that, the low-pass coefficient is given by,  $c_{j+1}(k) = \int dt \phi_{j+1,k}(t)f(t)$ , where  $f(t)$  is the function or data under consideration. In the limit,  $j \rightarrow \infty$ , the scaling function tends to the Dirac delta function; hence the corresponding low-pass coefficient  $c_{j \rightarrow \infty}(k)$  is the value of the function at location  $k$ . Therefore, starting from the values of the function at the highest resolution, one can find all the scaling and high-pass coefficients, without explicitly knowing the wavelet basis elements.

In a broad sense, the low-pass coefficients capture the trend and the high-pass coefficients keep track of the fluctuations in the data. In case of the simplest Haar wavelet ( $n=2$ ),  $h(0)=h(1)=1/\sqrt{2}$ , and  $\tilde{h}(0)=-\tilde{h}(1)=1/\sqrt{2}$ . The low-pass and high-pass or wavelet coefficients are, respectively, the averages and differences of data points. In case of other discrete wavelets, these coefficients are appropriately weighted averages and differences. For example, Daubechies-4 (DB4) wavelet is characterized by four filter coefficients. It is worth mentioning that, the Daubechies family of wavelets are made to satisfy vanishing moments conditions,  $\int dt t^m \psi_{j,k}(t) = 0$ . This makes them blind to variations in a data set, which can be captured by polynomials of suitable degree, thereby making them ideal for separating fluctuations from average behavior. This property will be made use of extensively in the present paper. Wavelets are naturally endowed with an appropriate window size, which manifests in the scale index or level, and hence can capture the local averages and differences, in a window of one's choice.

The data for wavelet analysis is assumed to be of the size  $2^L$ , in case the same is not available recourse is taken to padding. In the present analysis, we have used constant padding at the ends. For the above data, one can have a maximum  $L$  level decomposition, although one can stop at any level below  $L$ . The level-1 high-pass coefficients are half the size of the data and represent fluctuations at the lowest scale. The progressively higher level coefficients represent fluctuations at larger scales; the low-pass coefficients at a given level represent the appropriately averaged data, commensurate with the window size of the level concerned. It should be mentioned that, for wavelets other than Haar, artifacts, both in low- and high-pass coefficients, arise at the endpoints, due to the need for circular or other forms of required extensions. We have used constant padding at both the ends, discarding the coefficients originating from them, to avoid the edge effect because of wrapping of wavelet filters by the convolution process during decomposition.

In the present approach, a time series or the cumulative distribution in case of binomial multifractal data have been subjected to a multilevel decomposition. Reconstructed series after removal of successive high-pass coefficients was subtracted from the data to extract the fluctuations,  $F(s)$  as a function of scale  $s$ . Here,  $s$  denotes the level of decomposition. As is clear, reconstruction after removing the first level high-pass coefficients achieves coarse graining in a window size, which depends on the length of the filter coefficients. For a given wavelet, removal of other level high-pass coef-

TABLE I. The  $h(q)$  values of binomial multifractal series (BMFS) computed analytically (BMFS<sub>a</sub>), through MF-DFA (BMFS<sub>s</sub>) and wavelet (BMFS<sub>w</sub>) approach. For  $q < 0$ , DB4 and for  $q > 0$ , DB14 wavelets have been used.

$q$	$h(q)_{\text{BMFS}_a}$	$h(q)_{\text{BMFS}_s}$	$h(q)_{\text{BMFS}_w}$
-10.0000	1.9000	1.7544	1.7534
-9.0000	1.8889	1.7439	1.7558
-8.0000	1.8750	1.7307	1.7588
-7.0000	1.8572	1.7138	1.7627
-6.0000	1.8337	1.6914	1.7677
-5.0000	1.8012	1.6605	1.7746
-4.0000	1.7544	1.6154	1.7845
-3.0000	1.6842	1.5470	1.7998
-2.0000	1.5760	1.4551	1.8224
-1.0000	1.4150	1.3802	1.6806
0	0	0	0
1.0000	1.0000	0.9923	1.0316
2.0000	0.8390	0.8169	0.8538
3.0000	0.7309	0.6995	0.7384
4.0000	0.6606	0.6253	0.6660
5.0000	0.6139	0.5771	0.6193
6.0000	0.5814	0.5444	0.5878
7.0000	0.5578	0.5212	0.5655
8.0000	0.5400	0.5040	0.5490
9.0000	0.5261	0.4907	0.5365
10.0000	0.5150	0.4803	0.5267

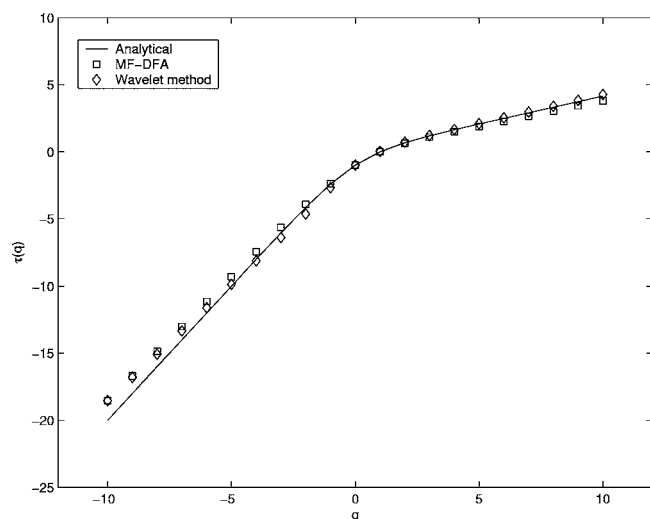


FIG. 3. Wavelet method ( $\diamond$ ) and MF-DFA ( $\square$ ) analysis of computer generated time series for binomial multifractal model show the dependence of  $\tau(q)$  on  $q$ , which compares quite well with the analytically calculated  $\tau(q)$  values (dashed line). For  $q < 0$ , DB4 and for  $q > 0$ , DB14 wavelets have been used

ficients enlarges the window size. As has been mentioned in the beginning, the fact that in Daubechies (DB) family of wavelets, the low-pass captures the appropriate polynomial behavior of the data set, makes them quite useful for our analysis. We have used DB4 to DB20 basis sets for comparison. It was observed, for the data under consideration here, that after a certain point, the improvements in the scaling exponents due to a higher wavelet was minimal.

Analogous to detrended fluctuation analysis, one can calculate the scaling exponents from the behavior of  $F_q(s)$  defined as

$$F_q(s) \equiv \left\{ \frac{1}{N} \sum_{k=1}^N |F(s)|^q \right\}^{1/q}. \quad (5)$$

Here  $q$  can take both positive and negative integral values, except zero. If the time series, under analysis, possesses fractal behavior, then  $F_q(s)$  reveals a power-law scaling,

$$F_q(s) \sim s^{h(q)}. \quad (6)$$

As noted earlier, if  $H$  is constant for all  $q$  then the series is monofractal, otherwise it is multifractal. For  $q < 0$ ,  $h(q)$  captures the scaling properties of the small fluctuations, whereas for  $q > 0$  those of the large fluctuations. Often, the scaling exponent  $h(q)$  is represented in terms of  $\tau(q)$ , where  $\tau(q) = qh(q) - 1$ .

In Table I, the  $h(q)$  values are given for the binomial multifractal time series, using analytical method, MF-DFA and the present discrete wavelet based approach. In MF-DFA, we have used a quadratic polynomial fit, to isolate the trend. A host of wavelets have been tested, the results shown here correspond to DB14 for  $q > 0$  and DB4 for  $q < 0$ , since the improvement was minimal after that.

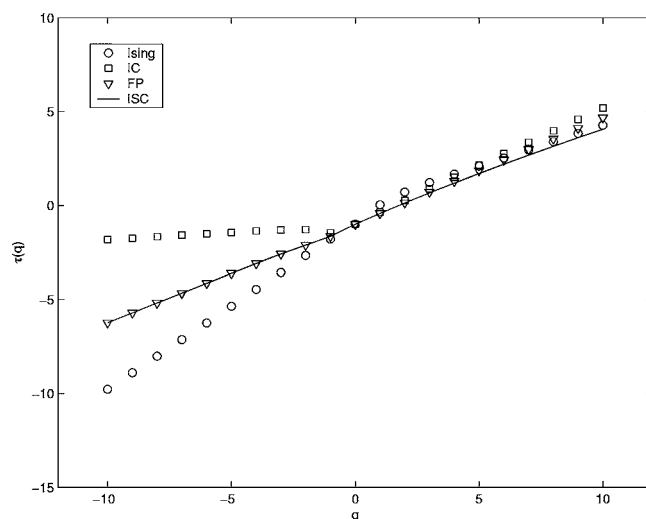


FIG. 4. Wavelet based fluctuation analysis of the experimental data (shown in Fig. 2) and spin density values of the 2D Ising model at  $T_c$ , shows the dependence of  $\tau(q)$  on various values of  $q$ .

As is clear from the table, for positive  $q$ , the wavelet estimate of the Hurst exponent for the binomial multifractal series is extremely reliable when compared with the analytical result. For  $q < 0$ , when DB14 was used in the wavelet based approach, smaller  $h(q)$  values were obtained. However,  $h(q)$  values decreased with increasing values of  $q$ . It was found that, the results for  $q < 0$  improves substantially if one uses a lower order Daubechies wavelet, e.g., DB4. It should be noted that, this amounts to capturing the trend by a lower order polynomial curve, like in the MF-DFA approach. Higher order wavelets, having a large number of filter coefficients average the data over a much bigger window size and hence are not expected to perform well in estimating the smaller fluctuations. Hence, in our analysis a higher order wavelet has been used for  $q > 0$  and a lower order one for  $q < 0$ . These results are shown in Fig. 3. Analysis of the scaling properties of the spin density fluctuations and experimental data sets reveal that the corresponding time series have multiscaling behavior, as is seen clearly in Fig. 4.

In conclusion, the wavelet based method presented here, for calculating the scaling exponents, is found to be quite efficient, fast in computation and reliable. It performed well for both synthesized and experimental data. Our method is well suited to characterize both large ( $q > 0$ ) and small ( $q < 0$ ) fluctuations. In the latter case, one needs to use a lower order wavelet, since the larger size of the filter coefficients of the higher order wavelets average over a bigger window size, thereby distorting the smaller fluctuations. As compared to MF-DFA, the discrete wavelet based approach has less number of windows. This procedure compliments the former in the sense that, fluctuations at different scales have been isolated by subtracting the local polynomial trend captured through Daubechies family of wavelets.

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